A58HM

RECOMMENDED APPLICATIONS





























MAC HINES





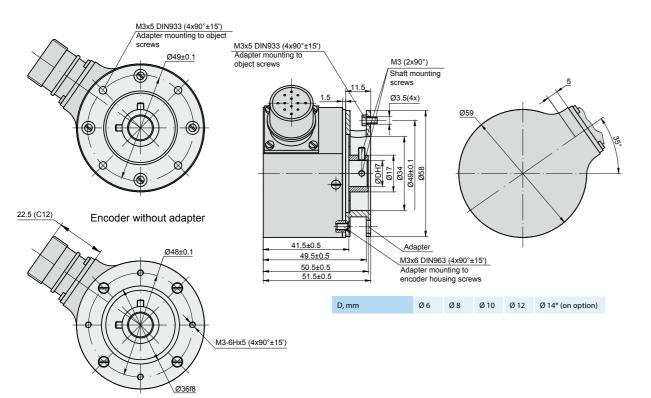




MECHANICAL DATA

Line number on disc (z)	100; 250; 500; 600; 800; 1000; 1024; 1125; 1250; 1500; 2000; 2500; 3000; 3600; 4000; 5000; 9000; 10800
Pulse number per shaft revolution for A58-F	Z x k, where k=1,2,3,4,5,8,10 (k - interpolation factor)
Maximum shaft speed	10000 rpm
Permissible motion of shaft: - axial - radial (at shaft end)	±0.03 mm 0.05 mm
Accuracy (T ₁ -period of lines on disc n arc. sec) - on option for z < 5000 - on option for z > 5000	±0.1T , arc. sec ±0.05T , arc. sec ±12.0 arc. sec

Starting torque at 20 °C	≤ 0.025 Nm
Rotor moment of inertia	< 1.5x10 ⁻⁴ kgm ²
Protection (housing) (IEC 529)	IP 64
Protection (shaft side) (IEC 529)	IP64
Maximum weight without cable	0.35 kg
Operating temperature	0+70 °C
Storage temperature	-30+80 °C
Maximum humidity (non-condensing)	98 %
Permissible vibration (55 to 2000 Hz)	\leq 100 m/s 2
Permissible shock (11 ms)	\leq 300 m/s 2



ELECTRICAL DATA

VERSION	A58 HE-A ~ 11 μApp	A58 HE-AV \sim 1 V pp	A58 HE-F ☐ TTL; ☐ HTL	
Supply voltage (U _p)	+5 V ± 5%	+5 V ± 5%	+5 V ± 5%; +(10 to 30) V	
Max. supply current (without load)	80 mA	120 mA	120 mA	
Light source	LED	LED	LED	
Incremental signals	Two sinusoidal I, and I, Amplitude at 1 k Ω load: - I1 = 7-16 μ A - I2 = 7-16 μ A	Differential sine +A/-A and +B/-B Amplitude at 120 Ω load: - A = 0.6-1.2 V - B = 0.6-1.2 V	Differential square-wave U1 $\overline{\text{U1}}$ and U2 $/\overline{\text{U2}}$. Signal levels at 20 mA load current: - low (logic "0") \leq 0.5 V at U $_p$ =+5 V - low (logic "0") \leq 1.5 V at U $_p$ =10 to 30 V - high (logic "1") \geq 2.4 V at U $_p$ =+5 V - high (logic "1") \geq (U $_p$ -2) V at U $_p$ =10 to 30 V	
Reference signal	One quasi-triangular l_0 peak per revolution. Signal magnitude at 1 k Ω load: $-l_0$ = 2-8 μ A (usable component)	One quasi-triangular +R and its complementary -R per revolution. Signals magnitude at 1200 load -R = 0.2-0.8 V (usable component)	One differential square-wave U0/U0 per revolution. Signal levels at 20 mA load current: - low (logic "0") < 0.5 V at U $_p$ =+5 V - low (logic "0") < 1.5 V at U $_p$ =10 to 30 V - high (logic "1") > 2.4 V at U $_p$ =+5 V - high (logic "1") > (U $_p$ -2) V at U $_p$ =10 to 30 V	
Maximum operating frequency	(-3 dB) ≥ 160 kHz	(-3 dB) ≥ 180 kHz	(160 x k) kHz, k-interpolation factor	
Direction of signals	l ₂ lags l ₁ for clockwise rotation	B lags A for clockwise rotation	U2 lags U1 with clockwise rotation	
Maximum rise and fall time	-	-	< 0.5 μs	
Standard cable length	1 m, without connector	1 m, without connector	1 m, without connector	
Maximum cable length	5 m	25 m	25 m	
Output signals	1 ₂ 1 ₀ 90° et. 360° et.	+A +B +R 90° el. 135° el. 360° el.	a=0.25T±0.125T T aaaa U1 U1 U1 U2 U2 U2 U2 U0 a	

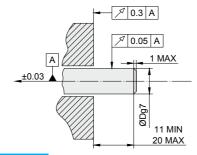
Note:

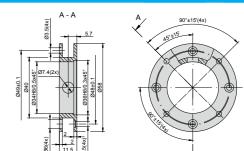
1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanical rotation speed.

ADAPTER

2. If cable extension is used, power supply conductor cross-section should not be smaller than 0.5 mm

MOUNTING DIMENSIONS

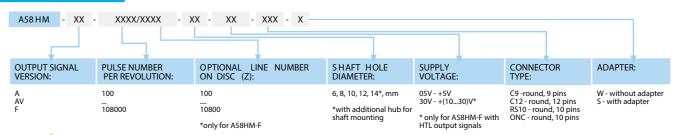




ACCESSORIES

CONNECTORS FOR CABLE	C9 12-pin round connector	C12 12-pin round connector	RS10 10-pin round connector	ONC 10-pin round connector		
DIGITAL READOUT DEVICES	CS3000			CS5500		
EXTERNAL INTERPOLATOR			NK			

ORDER FORM





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MAIN EXPORT COUNTRIES:





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The company's goal is to consistently supply high quality products and services to meet customer demands on a timely basis. The company's meeting the company's meeting the company of the products are linear and angular glass scale gratings, and the linear and rotary displacement measuring systems.

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The encoder A58HM is used to measure angular position of the key machine components, industrial robots, comparators, rotary tables, servo drives and to establish an informational link with DCC, NC or Digital Readout Units. The encoder has integrated stator c oupling so it can be fixed directly onto object shaft. Mounting adapter - similar to adapter of encoder A58H - is available on request. The encoder is used in automatic control, on-line gauging, process monitoring systems, etc. The housing of the encoder is fixed to an object by means of four screws M3 or through adapter. The fixation to object shaft is made by two screws M3. Three versions of output signals are available:

- A58HM-A sinusoidal signals, with amplitude approx. 11 μApp;
- A58HM-AV sinusoidal signals, with amplitude approx. 1 Vpp;
- A58HM-F square-wave signals (TTL or HTL) with integrated subdividing electronics for interpolation x1, x2, x3, x4,x5, x8, x10.













