# **MAIN EXPORT COUNTRIES:**





The company under the nd&@"Precizika Metrology" began work after the change of name of the Lithuanian - American Joint Venture "Brown workforce has been involved for over fifty years in the supply of measuring technology and systems to automate factories as well as in the development of optical scale manufacturing technology.

In 2000, the production process was certified to fully meeting the requirements of EN ISO 9002:1994, in 2003 – EN ISO 9001:2000.

The company's goal is to consistently supply high quality products and services to meet customer demands on a timely basis. The company's minute of the company's manufacturing technology. & Sharpe - Precizika". The company has a proud history of old traditions in the leadership of design and production of metrological equipment. Its

products are linear and angular glass scale gratings, and the linear and rotary displacement measuring systems.

JSC "Precizika Metrology" represents worldwide known companies and suppliers of measuring equipment, CNC centers, executes installation and PHOTOELECTRIC ROTARY ENCODER services of them, trains the users, and executes upgrading of used CMM and manual cutting machine-tools.





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The encoder A58H1 is used to measure angular position of the key machine components, industrial robots, comparators, rotary tables, servo drives and to establish an informational link with DCC, NC or Digital Readout Units. The encoder has external flexible coupling. The encoder is used in automatic control, on-line gauging, process monitoring systems, etc. Three versions of output signals are available:

- A58H1-A sinusoidal signals, with amplitude approx. 11 µApp;
- A58H1-AV sinusoidal signals, with amplitude approx. 1 Vpp;
- A58H1-F square-wave signals (TTL) with integrated subdividing electronics for interpolation x1, x2, x3, x4, x5, x8, x10.













# A58H1

### RECOMMENDED APPLICATIONS

























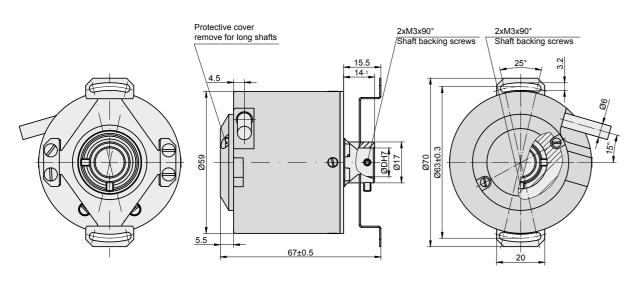


MACH INES

### MECHANICAL DATA

Line number on disc (z)	100 ;250; 500; 600; 800; 1000; 1024; 1125; 1250; 1500; 2000; 2500; 3000; 3600; 4000; 5000; 9000; 10800
Pulse number per shaft revolution for A58H1-F	Z x k, where k=1,2,3,4,5,8,10
Maximum shaft speed	10000 rpm
Permissible motion of shaft: - axial - radial (at shaft end)	±0.03 mm 0.05 mm
Accuracy (T 1-period of lines on disc in arc. sec)	±0.1T <sub>1</sub> arc. sec
Starting torque at 20 °C	≤ 0.025 Nm

Rotor moment of inertia	< 1.5x10 <sup>-4</sup> kgm <sup>2</sup>		
Protection (housing) ( IEC 529)	IP64		
Protection (shaft side) ( IEC 529)	IP64		
Maximum weight without cable	0.3 kg		
Operating temperature	-10+70 °C		
Storage temperature	-30+80 °C		
Maximum humidity (non-condensing)	98 %		
Permissible vibration (55 to 2000 Hz)	$\leq 100$ m/s $^{2}$		
Permissible shock (11 ms)	$\leq$ 300 m/s $^2$		



Ø 6 Ø 8 Ø 10 Ø 12 Ø 14\* (on option)

### **ELECTRICAL DATA**

VERSION	A58H1-A ~ 11 μApp	A58H1-AV	A58H1-F П□TTL; П□HTL		
			,		
Supply voltage (U <sub>p</sub> )	+5 V ± 5%	+5 V ± 5%	+5 V ± 5%; +(10 to 30) V		
Max. supply current (without load)	80 mA	120 mA	120 mA		
Light source	LED	LED	LED		
Incremental signals	Two sinusoidal I, and I, Amplitude at 1 k $\Omega$ load: - 11 = 7-16 $\mu$ A - 12 = 7-16 $\mu$ A	Differential sine +A/-A and +B/-B Amplitude at $120 \Omega$ load: - A = 0.6-1.2 V - B = 0.6-1.2 V	Differential square-wave $U1\overline{J1}$ and $U2/\overline{U2}$ . Signal levels at 20 mA load current:  - low (logic "0") $\leq 0.5$ V at U $_p$ =+5 V  - low (logic "0") $\leq 1.5$ V at U $_p$ =10 to 30 V  - high (logic "1") $\geq 2.4$ V at U $_p$ =+5 V  - high (logic "1") $\geq (U_p \cdot 2)$ V at U $_p$ =10 to 30 V		
Reference signal	One quasi-triangular $I_0$ peak per revolution. Signal magnitude at 1 k $\Omega$ load: - $I_0$ = 2-8 $\mu$ A (usable component)	One quasi-triangular +R and its complementary -R per revolution. Signals magnitude at 120Ω load -R = 0.2-0.8 V (usable component)	One differential square-wave U0/U0 per revolution. Signal levels at 20 mA load current: - low (logic "0") < 0.5 V at U $_p$ =+5 V - low (logic "0") < 1.5 V at U $_p$ =10 to 30 V - high (logic "1") > 2.4 V at U $_p$ =+5 V - high (logic "1") > (U $_p$ -2) V at U $_p$ =10 to 30 V		
Maximum operating frequency	$(-3 \text{ dB}) \ge 160 \text{ kHz}$	$(-3 \text{ dB}) \ge 180 \text{ kHz}$	(160 x k) kHz, k-interpolation factor		
Direction of signals	L lags I, for clockwise rotation (viewed fromshaft side)	+B lags +A for clockwise rotation (viewed fromshaft side)	U2 lags U1 with clockwise rotation (viewed from shaft side)		
Maximum rise and fall time	-	н	< 0.5 μs		
Standard cable length	1 m, without connector	1 m, without connector	1 m, without connector		
Maximum cable length	5 m	25 m	25 m		
Output signals	l <sub>1</sub> l <sub>2</sub> l <sub>0</sub> 90° el. 135° el. 360° el.	+A +B +R 90° el. 135° el. 360° el.	a=0.25T±0.125T  T a a a a  U1 U1 U2 U2 U2 U0 U0 u0		

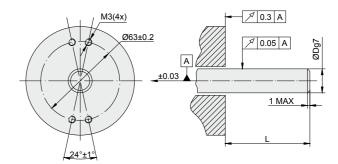
### Note:

- 1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanica rotation speed.
- 2. If cable extension is used, power supply conductor cross-section should not be smaller than 0.5 mm

ELEKTRİK ELEKTRONİK MALZEMELERİ SAN. VE TİC. LTD. ŞTİ.

### **MOUNTING REQUIREMENTS**

11 min for one side fixation 56 min for both side fixation 56 max for version with protective cover 11 min for version without protective cover



### **ACCESSORIES**

CONNE CT ORS FOR CABL E	B12 12-pin round connector	C9 12-pin round connector	C12 12-pin round connector	D9 9-pin flat connector	D15 15-pin flat connector	RS10 10-pin round connector	ONC 10-pin round connector
DIGITAL RE ADOUT D EVICES	CS3000			CS5500			
EXTERN AL INTER POLAT OR				NK			

## **ORDER FORM**



<sup>\*</sup>For one side fixation from encoder flange side