MAIN EXPORT COUNTRIES:



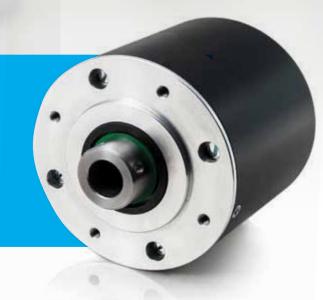


The company under the nd&@"Precizika Metrology" began work after the change of name of the Lithuanian - American Joint Venture "Brown **458**H & Sharpe - Precizika". The company has a proud history of old traditions in the leadership of design and production of metrological equipment. Its workforce has been involved for over fifty years in the supply of measuring technology and systems to automate factories as well as in the developmen of optical scale manufacturing technology.

In 2000, the production process was certified to fully meeting the requirements of EN ISO 9002:1994, in 2003 – EN ISO 9001:2000.

The company's goal is to consistently supply high quality products and services to meet customer demands on a timely basis. The company's m products are linear and angular glass scale gratings, and the linear and rotary displacement measuring systems.

JSC "Precizika Metrology" represents worldwide known companies and suppliers of measuring equipment, CNC centers, executes installation and PHOTOELECTRIC ROTARY ENCODER services of them, trains the users, and executes upgrading of used CMM and manual cutting machine-tools.





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The encoder A58H is used to measure angular position of the key machine components, industrial robots, comparators, rotary tables, servo drives and to establish an informational link with DCC, NC or Digital Readout Units. The encoder has integrated stator c oupling so it can be fixed directly onto shaft. Mounting adapter is available on request. The encoder is used in automatic control, on-line gauging, process monitoring systems, etc. The case of encoder is mounted via four screws M3 or through adapter. Encoder is coupled via sleeve coupling, backing screws are provided on both sides of the coupling. Three versions of output signals are available:

- A58H-A sinusoidal signals, with amplitude approx. 11 μApp;
- A58H-AV sinusoidal signals, with amplitude approx. 1 Vpp;
- A58H-F square-wave signals (TTL) with integrated subdividing electronics for interpolation x1, x2, x3, x4, x5, x8, x10.















A58H

RECOMMENDED APPLICATIONS





















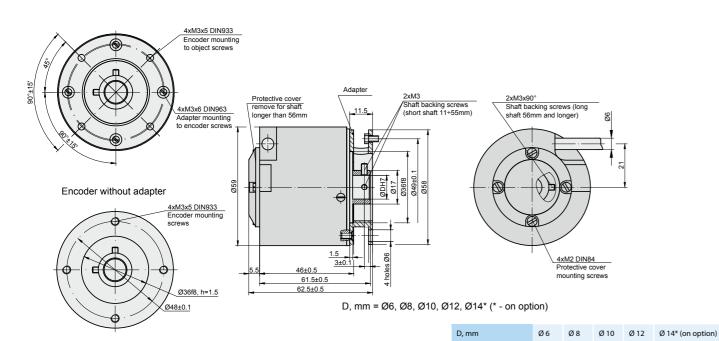
MILLI NG / B ORI NG / DRILLI NG CNC MACHI NES

MACHI NE S

MECHANICAL DATA

	Line number on disc (z)	100;250; 500; 600; 800; 1000; 1024; 1125; 1250; 1500; 2000; 2500; 3000; 3600; 4000; 5000; 9000; 10800	
	Pulse number per shaft revolution for A58-F	Z x k, where k=1,2,3,4,5,8,10	
	Maximum shaft speed	10000 rpm	
	Permissible motion of shaft: - axial - radial (at shaft end)	±0.03 mm 0.05 mm	
	Accuracy (T ,-period of lines on disc in arc. sec) - on option for z < 5000 - on option for z > 5000	±0.1T ₁ arc. sec ±0.05T ₁ arc. sec ±12.0 arc. sec	

Starting torque at 20 °C	≤ 0.025 Nm		
Rotor moment of inertia	< 1.5x10 ⁻⁴ kgm ²		
Protection (housing) (IEC 529)	IP64		
Protection (shaft side) (IEC 529)	IP 64		
Maximum weight without cable	0.35 kg		
Operating temperature	-10+70 °C		
Storage temperature	-30+80 °C		
Maximum humidity (non-condensing)	98 %		
Permissible vibration (55 to 2000 Hz)	≤ 100 m/s 2		
Permissible shock (11 ms)	< 300 m/s ²		

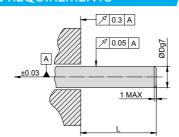


ELECTRICAL DATA

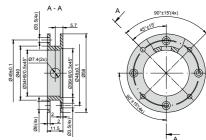
A58H-A ~11 μApp	A58H-AV ~1 V pp	A58H-F П☐ TTL; П☐ HTL		
+5 V ± 5%	+5 V ± 5%	+5 V ± 5%; +(10 to 30) V		
80 mA	120 mA	120 mA		
LED	LED	LED		
Two sinusoidal I, and I, Amplitude at 1 k Ω load: - I1 = 7-16 μ A - I2 = 7-16 μ A		Differential square-wave $U1\overline{J1}$ and $U2\overline{J2}$. Signal levels at 20 mA load current: - low (logic "0") ≤ 0.5 V at U $_p$ =+5 V - low (logic "0") ≤ 1.5 V at U $_p$ =10 to 30 V - high (logic "1") ≥ 2.4 V at U $_p$ =10 to 30 V - high (logic "1") $\geq (U_p$ -2) V at U $_p$ =10 to 30 V		
One quasi-triangular I_0 peak per revolution. Signal magnitude at 1 k Ω load: - I_0 = 2-8 μ A (usable component)	One quasi-triangular +R and its complementary -R per revolution. Signals magnitude at 120Ω load - R = 0.2-0.8 V (usable component)	One differential square-wave U0/U0 per revolution. Signal levels at 20 mA load current: - low (logic "0") < 0.5 V at U $_p$ =+5 V - low (logic "0") < 1.5 V at U $_p$ =10 to 30 V - high (logic "1") > 2.4 V at U $_p$ =10 to 30 V - high (logic "1") > (U $_p$ -2) V at U $_p$ =10 to 30 V		
$(-3 \text{ dB}) \ge 160 \text{ kHz}$	$(-3 \text{ dB}) \ge 180 \text{ kHz}$	(160 x k) kHz, k-interpolation factor		
l, lags l, for clockwise rotation (viewed fromshaft side)	+B lags +A for clockwise rotation (viewed fromshaft side)	U2 lags U1 with clockwise rotation (viewed from shaft side)		
-	-	< 0.5 μs		
1 m, without connector	1 m, without connector	1 m, without connector		
5 m	25 m	25 m		
I ₁ I ₂ I ₀ 90° eL 135° eL 360° eL	+A +B +R 90° eL 135° eL 360° eL	a=0.25T±0.125T T a a a a U1 U1 U2 U2 U2 U2 U0 U0 U0		
	+5 V ± 5% 80 mA LED Two sinusoidal I, and I, Amplitude at 1 kΩ load: - I1 = 7-16 μA - I2 = 7-16 μA One quasi-triangular I, peak per revolution. Signal magnitude at 1 kΩ load: - I = 2-8 μA (usable component) (-3 dB) \geq 160 kHz I, lags I, for clockwise rotation (viewed fromshaft side) 1 m, without connector 5 m I I I I I I I I I I	+5 V ± 5% 80 mA 120 mA LED Two sinusoidal I, and I, Amplitude at 1 kΩ load: - I1 = 7-16 μA - I2 = 7-16 μA - I2 = 7-16 μA One quasi-triangular I, peak per revolution. Signal magnitude at 1 kΩ load: - I $_0$ = 2-8 μA (usable component) (-3 dB) \geq 160 kHz L lags I, for clockwise rotation (viewed fromshaft side) - 1 m, without connector 1 m, without connector 1 m, without connector 1 m, without connector		

- 1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanical rotation speed.
- 2. If cable extension is used, power supply conductor cross-section should not be smaller than 0.5 mm ².

MOUNTING REQUIREMENTS



ADAPTER



ACCESSORIES

CO NNE CTORS FOR CABL	E	B12 12-pin round connector	C9 12-pin round connector	C12 12-pin round connector	D9 9-pin flat con - nector	D15 15-pin flat connector	RS10 10-pin round connector	ONC 10-pin round connector
DIGITAL R EADOUT D EVIC	CS3000			CS5500				
EXT ER NAL I NTERPOLATO				NK				

ORDER FORM

