MAIN EXPORT COUNTRIES:





The company under the nd&@"Precizika Metrology" began work after the change of name of the Lithuanian - American Joint Venture "Brown & Sharpe - Precizika". The company has a proud history of old traditions in the leadership of design and production of metrological equipment. Its

products are linear and angular glass scale gratings, and the linear and rotary displacement measuring systems.

JSC "Precizika Metrology" represents worldwide known companies and suppliers of measuring equipment, CNC centers, executes installation and PHOTOELECTRIC ANGLE ENCODER services of them, trains the users, and executes upgrading of used CMM and manual cutting machine-tools.





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Precision photoelectric angle encoder A170 is used for precise angular displacement measurement of rotary tables, dividers, comparators, antennas and other high precision equipment. It provides information about the value and direction of motion. The encoder is used in au tomatic control, on-line gauging, process monitoring systems, etc. The stainless steel case of the encoder is mounted using screws. The angle encoder is connected to the motor shaft or spindle via coupling, available optionally. Three versions of output signals are available:

- A170-A sinusoidal signals, with amplitude approx. 11 µApp;
- A170-AV sinusoidal signals, with amplitude approx. 1 Vpp;
- A170-F square-wave signals (TTL) with integrated subdividing electronics for interpolation x1, x2, x5, x10, x20, x25, x50 and x100.

The modification with distance-coded reference marks is available

















A170

RECOMMENDED APPLICATIONS



















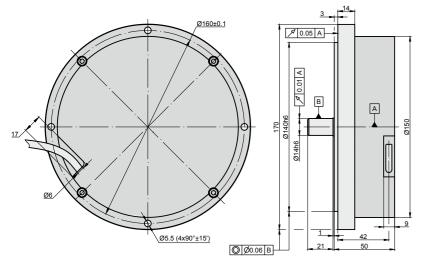


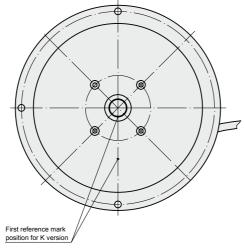
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MECHANICAL DATA

Line number	18000, 36000
Number of output pulses per revolu - tion for A170H-F	18000; 36000; 72000; 90000; 180000; 360000; 720000; 450000; 900000; 1800000; 3600000
Reference signal: - standard (S) - distance-coded (K) for z = 18000 - distance-coded (K) for z = 36000	one per shaft 36 per shaft revolution 72 per shaft revolution
Permissible mech. speed	≤ 1000 rpm
Max. operating speed (depends on number of output pulses)	300 to 500 rpm
Accuracy	±2.0; ±2.5; ±5.0 arc. sec

Permissible shaft load: - axial - radial	≤ 30 N ≤ 30 N
Starting torque at 20 $^{\circ}\text{C}$	≤ 0.012Nm
Rotor moment of inertia	< 3.7×10 ⁻⁴ kgm ²
Protection (IEC 529)	IP64
Maximum weight without cable	3.5 kg
Operating temperature	0+70 °C
Storage temperature	-30+85 °C
Maximum humidity (non condensing)	98 %
Permissible vibration	\leq 100 m/s 2
Permissible shock (6 ms)	\leq 300 m/s 2





ELECTRICAL DATA

VER SION	A170-A ~11 μApp	A170-A V ~ 1 Vpp	A170-F □ ∏L	
Supply voltage (U _p)	$+5 \text{ V} \pm 5\%$ 100 mA max.	$+5 \text{ V} \pm 5\%$ 120 mA max.	$+5 \text{ V} \pm 5\%$; 150 mA max.	
Light source	LED	LED	LED	
Incremental signals	Two sinusoidal I $_1$ and I $_2$ Amplitude at 1 k Ω load: -11 = 716 μ A -12 = 716 μ A	Differential sine +A/-A and +B/-B Amplitude at 120Ω load: - A = 0.61.2 V - B = 0.61.2 V	Differential square-wave U1, $\overline{U1}$ and U2/ $\overline{U2}$. Signal levels at 20 mA load current: - low (logic "0") \leq 0.5 V - high (logic "1") \geq 2.4 V	
Reference signal	One quasi-triangular I_0 peak per revolution. Signal magnitude at 1 k Ω load: $-I_0=28~\mu A$ (usable component)	One quasi-triangular +R and its complementary -R per revolution. Signals magnitude at 120Ω load - R = 28 V (usable component)	One differential square-wave U0/U0 per revolution. Signal levels at 20 mA load current: - low (logic "0") < 0.5 V - high (logic "1") > 2.4 V	
Maximum operating frequency	(-3 dB cutoff) \geq 160 kHz	(-3 dB cutoff) \geq 180 kHz	(160-2500 kHz (depends on interpolation factor)	
Direction of signals	${\bf I_2}$ lags ${\bf I_1}$ for clockwise rotation (viewed from encoder mounting side)	+B lags +A for clockwise rotation (viewed from encoder mounting side)	U2 lags U1 with clockwise rotation (viewed from encoder mounting side)	
Maximum rise and fall time	-	-	< 0.5 μs	
Standard cable length	1 m, without connector	1 m, without connector	1 m, without connector	
Maximum cable length	5 m	25 m	25 m	
Output signals	l ₁ l ₂ l ₀ 90° el. 360° el.	+A +B +R 90° eL 135° eL 360° eL	a=0.25T±0.125T T aaaa U1 U1 U1 U2 U2 U2 U0 a	

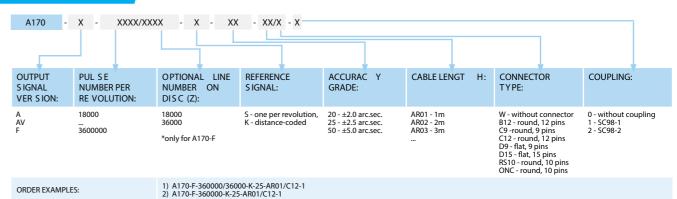
Note:

- 1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanical rotation speed.
- $2. \hspace{0.5cm} \text{If cable extension is used, power supply conductor cross-section should not be smaller than 0.5 mm} \\ \hspace{0.5cm}^{2}.$

ACCESSORIES

CONNECTOR S FOR CABLE	B12 12-pin round connector	C9 12-pin round connector	C12 12-pin round connector	D9 9-pin flat connector	D15 15-pin flat connector	RS10 10-pin round connector	ONC 10-pin round connector
DIGITAL READOUT DE VICE S		CS3000		CS5500			
COUPLING 5		SC98-1		SC98-2			
EXTERNAL INTERPOLATOR				NK			

ORDER FORM





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